

The MathWorks Today

Technical Computing and Model-Based Design

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Design Automation

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The MathWorks



MathWorks
Aerospace and Defense Conference '07

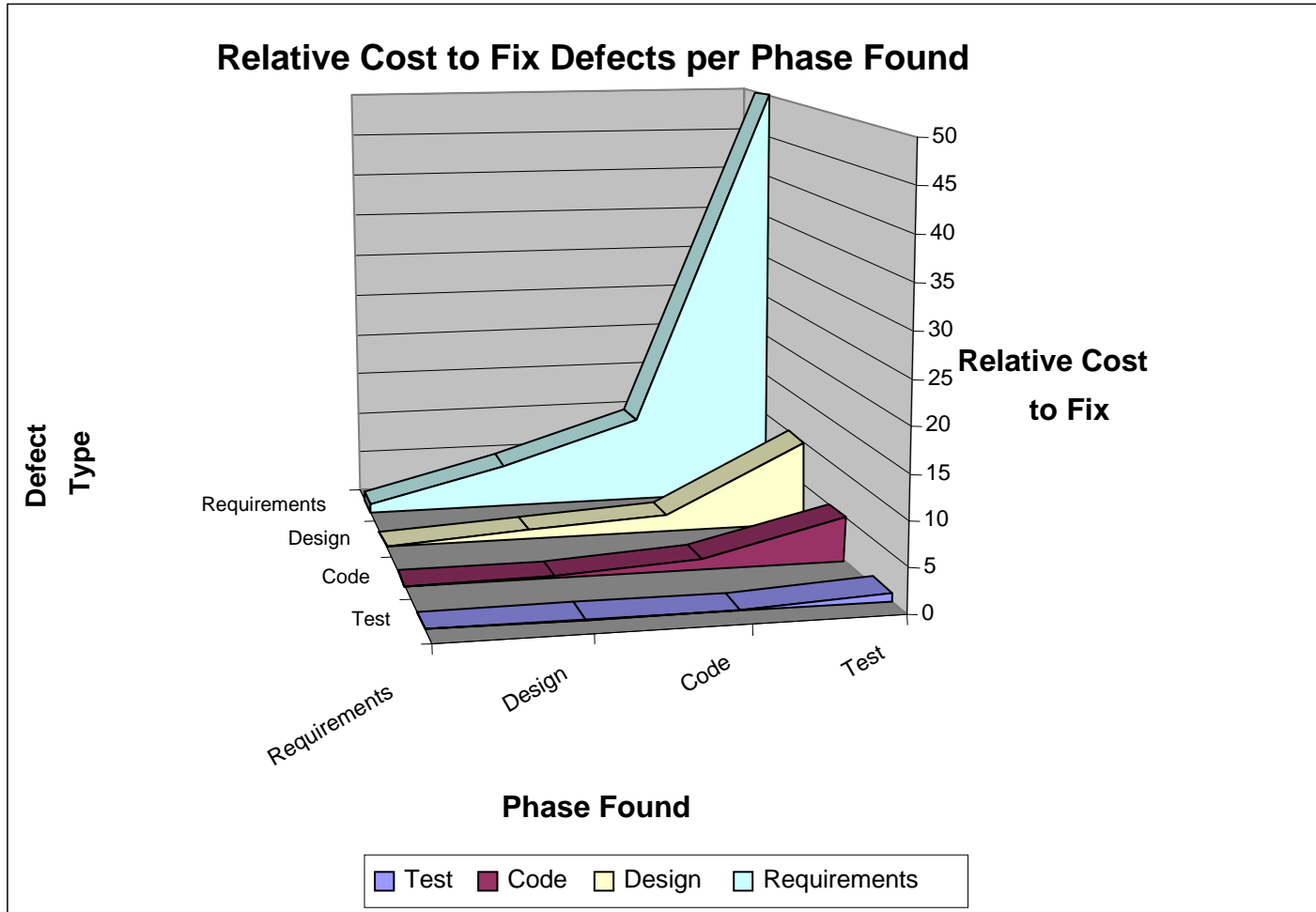
Common Themes in Aerospace

Time-to-market pressures,
regulatory guidelines,
risk management

Increased functionality,
more complexity,
difficult implementation choices

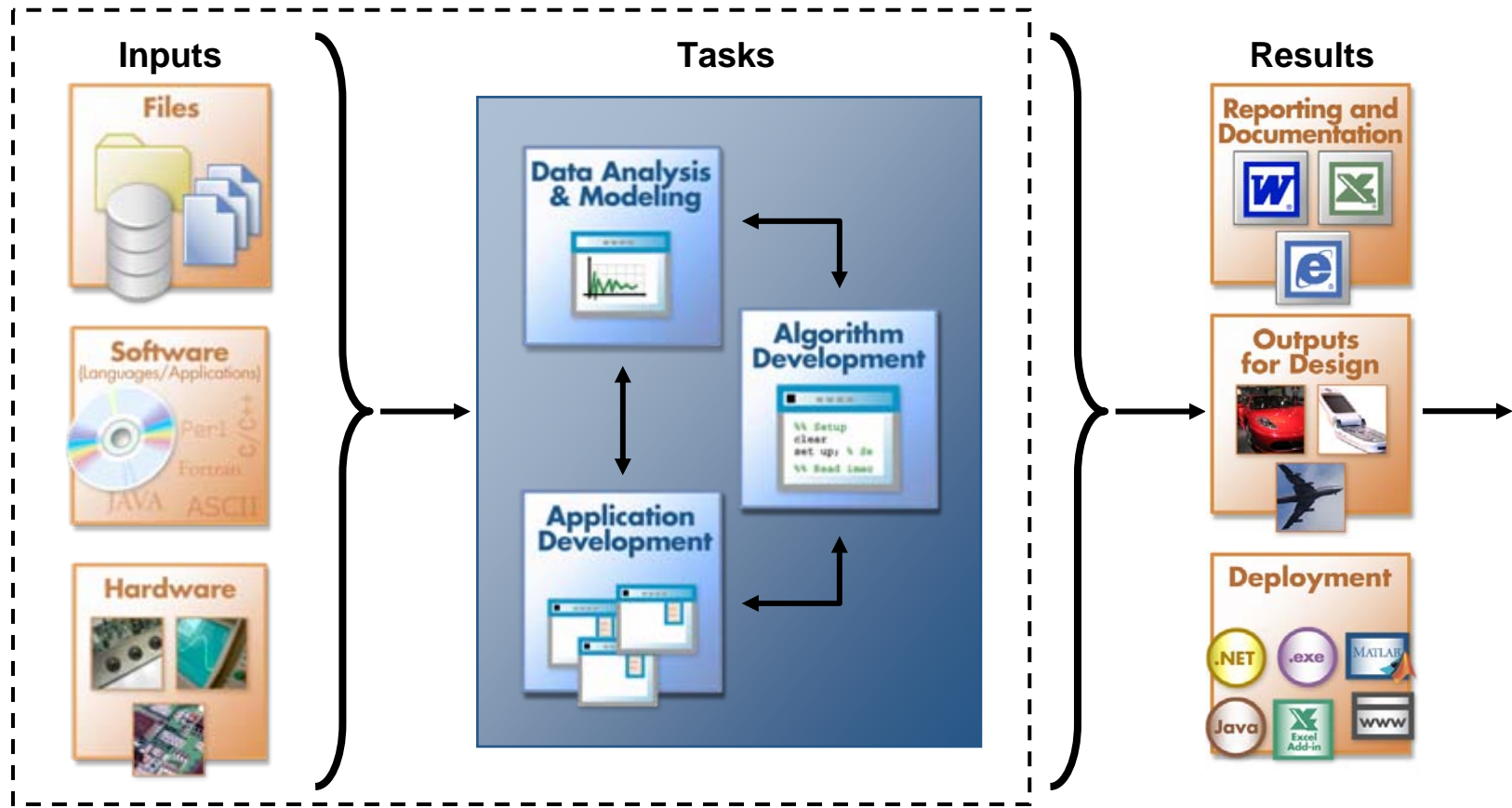
Distributed, multidisciplinary
development teams

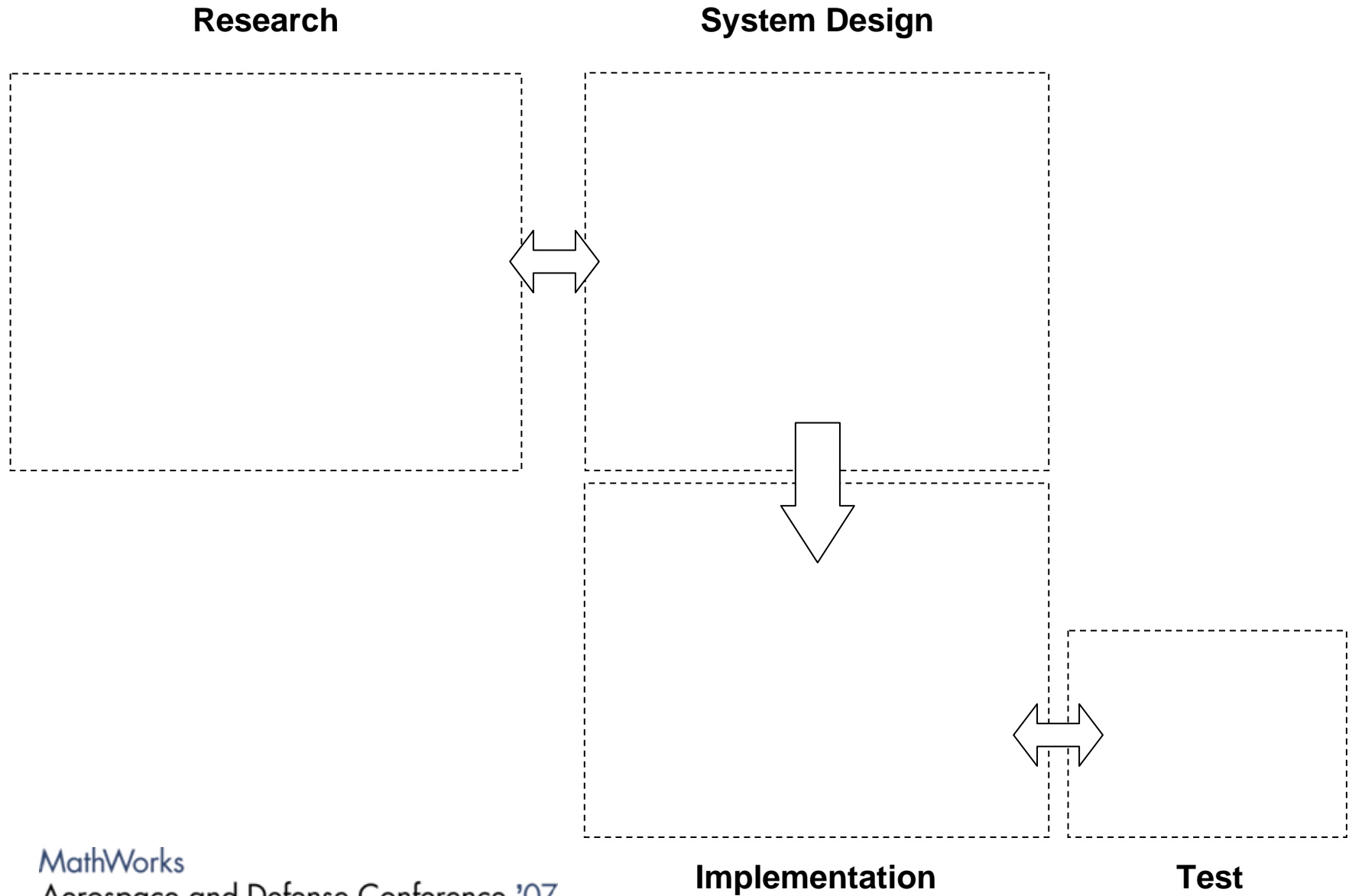
Differentiation by innovation



Source: Return on Investment for Independent Verification & Validation, NASA, 2004.

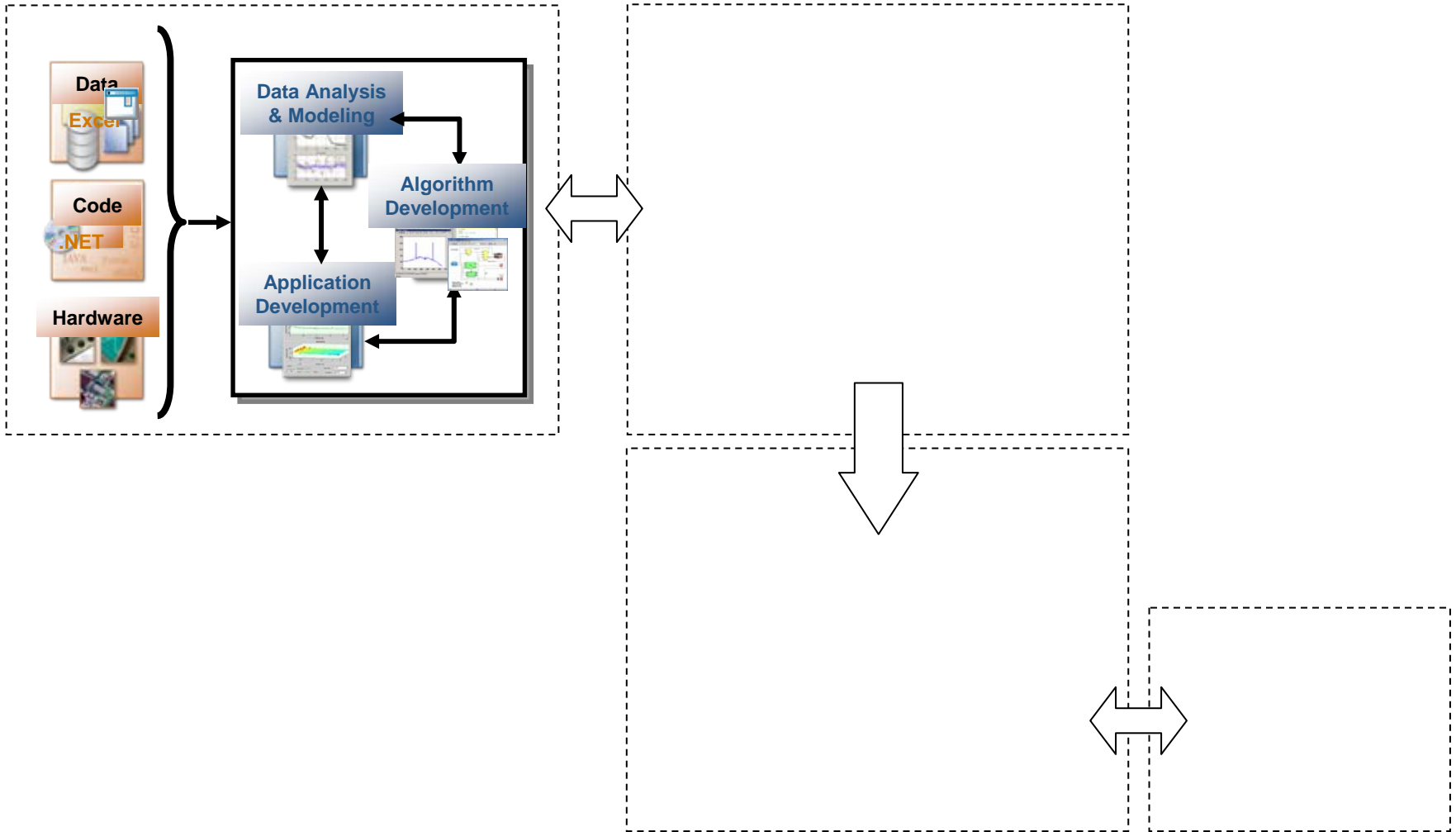
Technical Computing Workflow





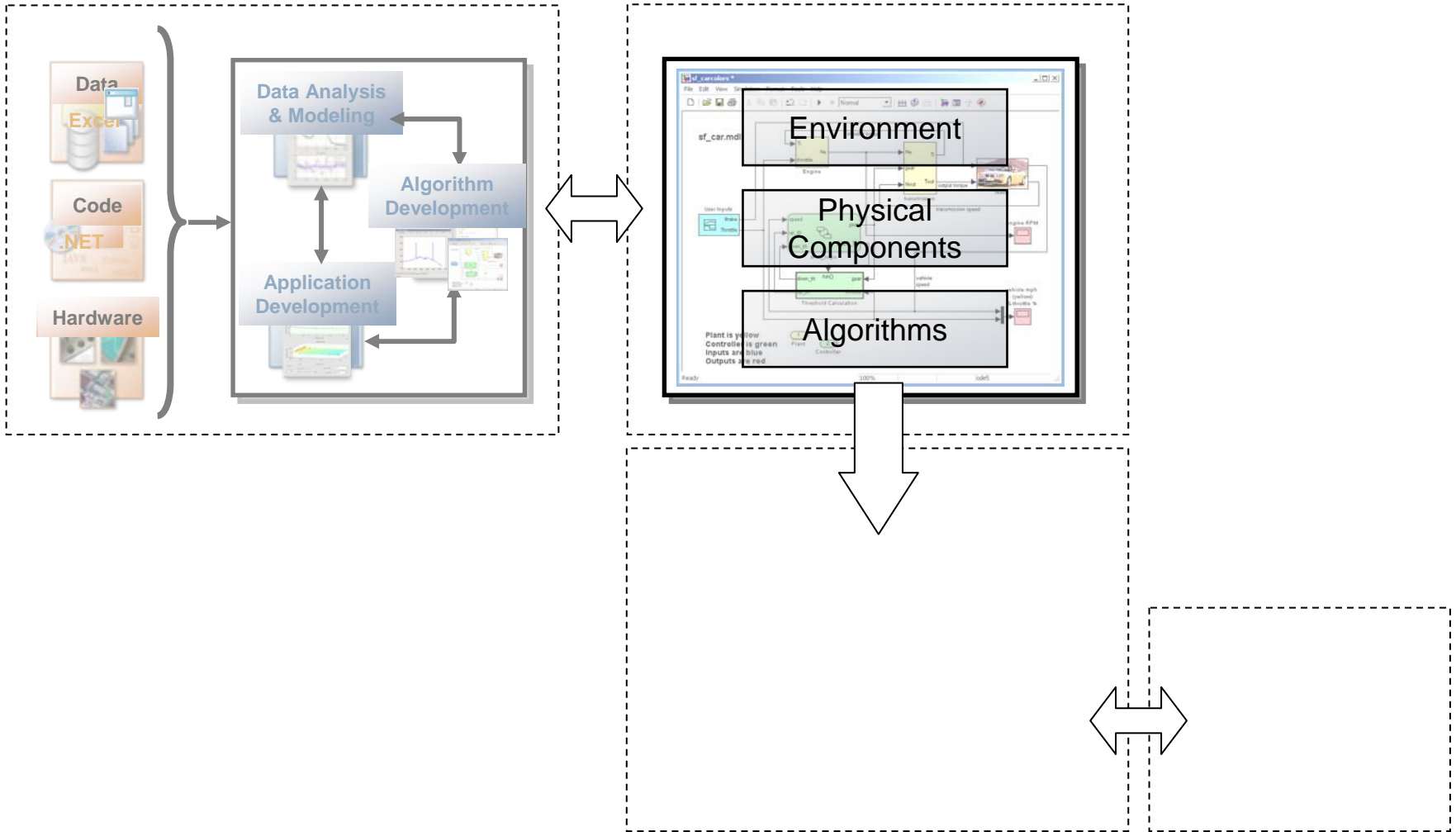
Research

System Design



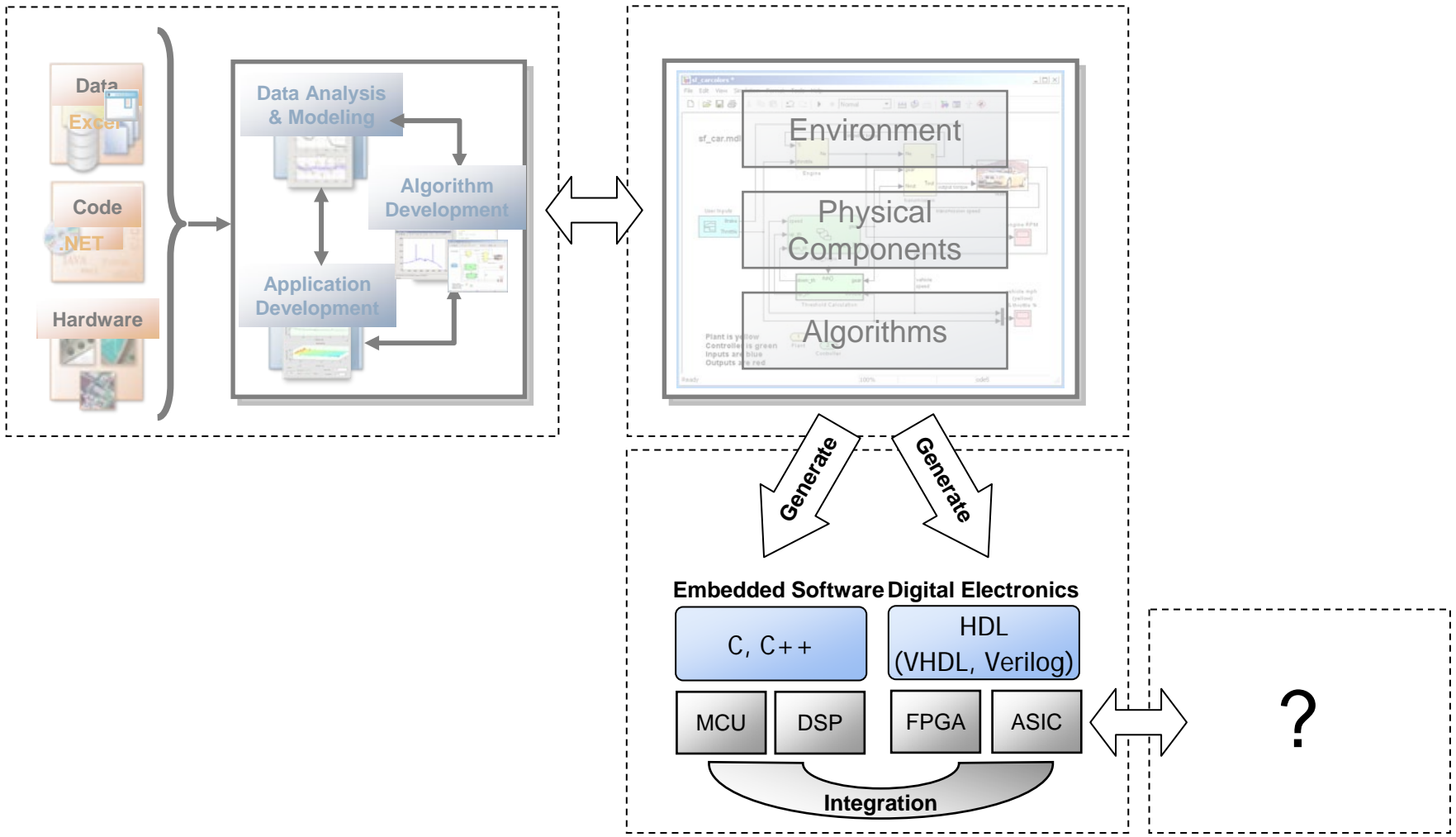
Research

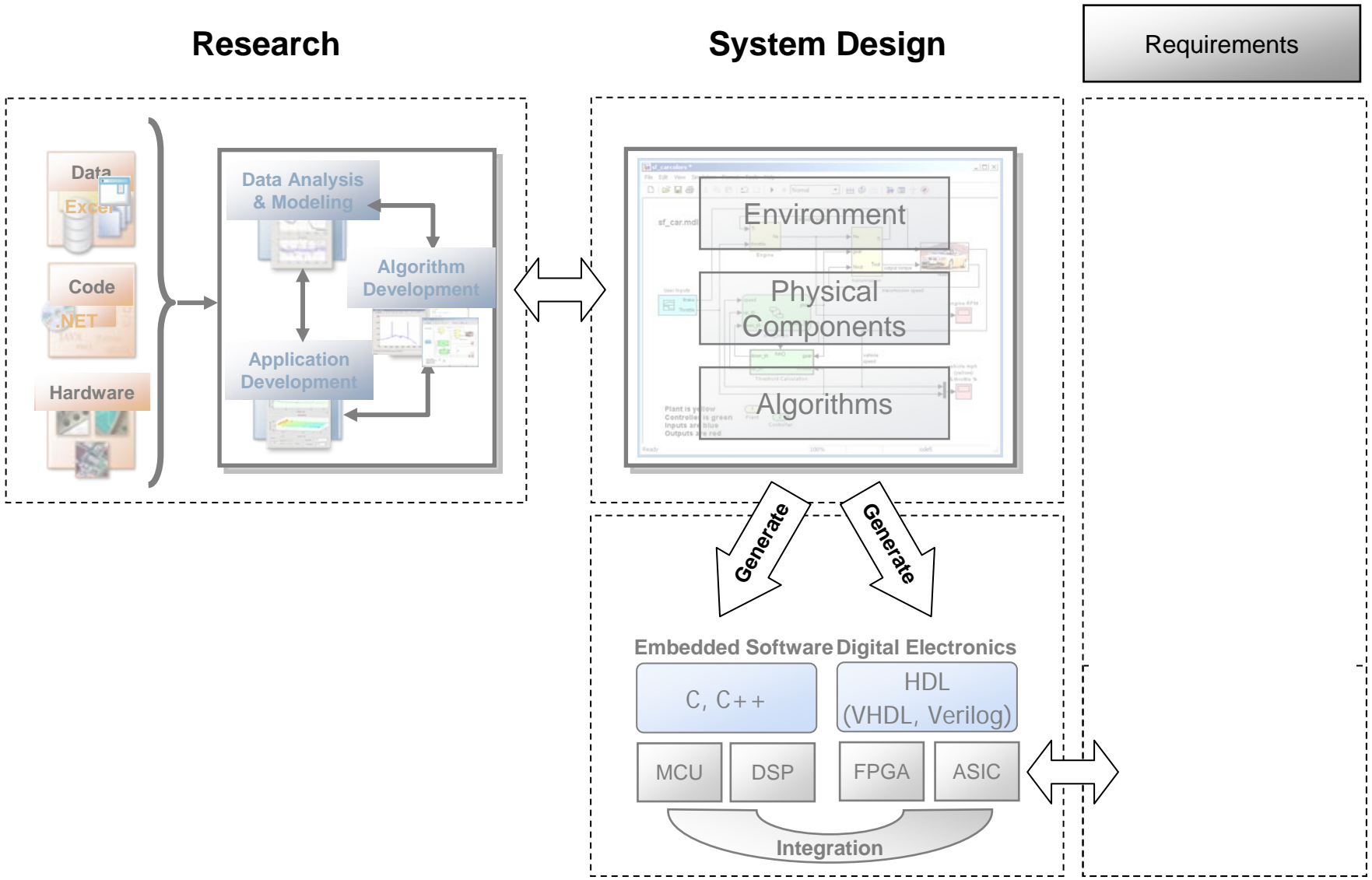
System Design



Research

System Design





Successful adoption of Model-Based Design in Aerospace and Defense

- Lockheed Martin
 - Flight control system for F-35 Joint Strike Fighter
 - Overall reduction in manhours/SLOC of ~40%
- Honeywell
 - Flight-control systems
 - Design times at Honeywell cut by 60%
- BAE SYSTEMS
 - Software-Defined Radio for satellite communications
 - Development time cut by 80%, Clocking and interfacing simplified
- Flying-Cam
 - Autonomous mini-helicopter controller
 - Development time reduced, error-free implementation
- NASA Hyper-X
 - Flight control software for X-43A scramjet vehicle
 - Development time reduced by months
- Swedish Space Corporation
 - Attitude and orbit control system for lunar satellite
 - System development reduced - 50%



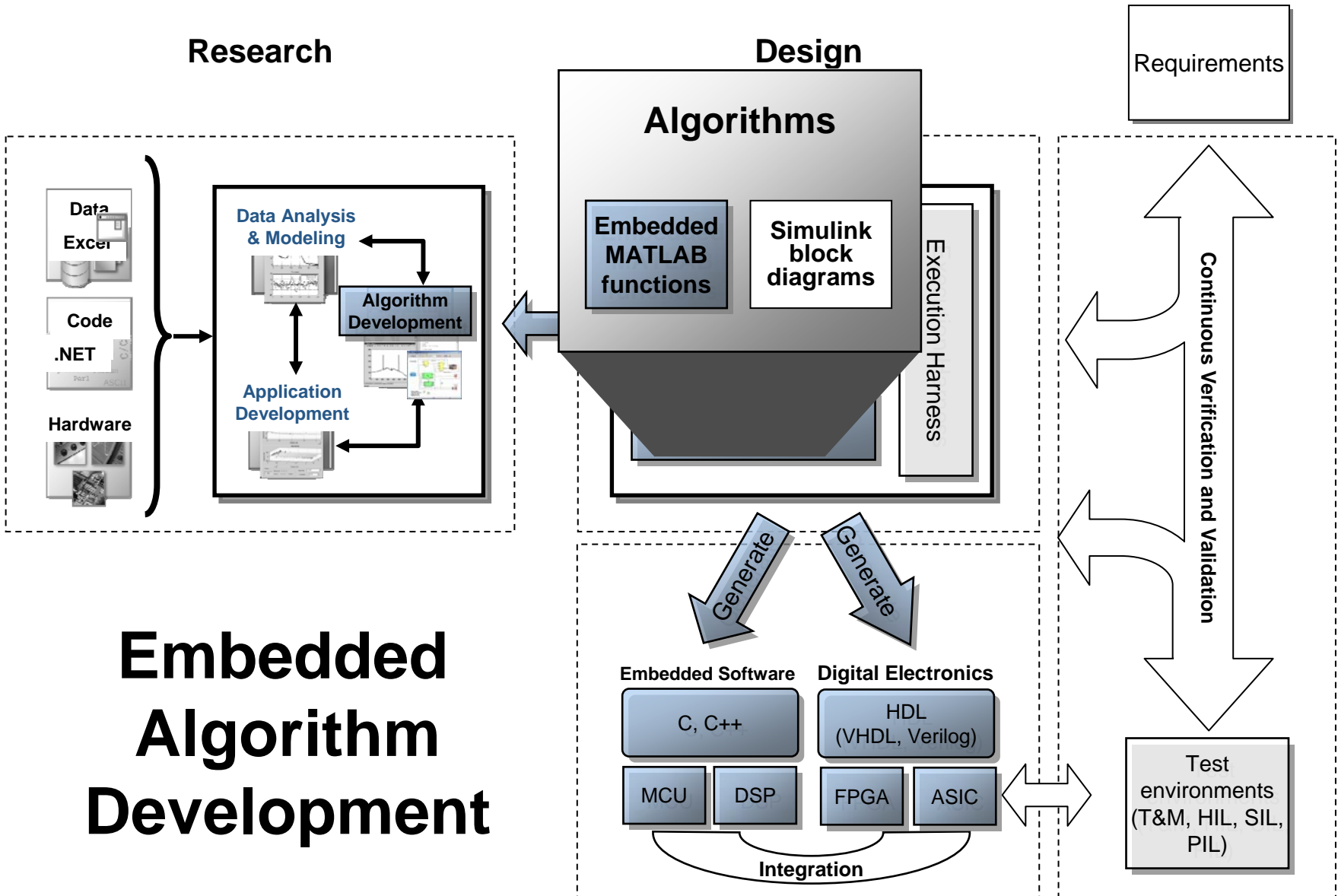
Successful Adoption of Model-Based Design in Communications and Electronics

- **Broadcom**
 - UMTS processor development
 - Development time cut by half compared to C coding
- **BridgeWave Communications**
 - Building-to-building wireless Ethernet
 - Cut development time from eight months to five
- **Realtek**
 - Audio processing codec chip
 - Reported higher return on investment
- **Yokogawa Electric**
 - Optical network components
 - 50% improvement in development time
 - Coding errors fixed before hardware testing



Key Technology Investment Areas

- Embedded MATLAB
- Multidomain Modeling and Simulation
- Video and Image Processing
- Verificaton and Validation
- Flight Code Generation
- HDL
- Distributed Computing



Embedded Algorithm Development

Embedded MATLAB



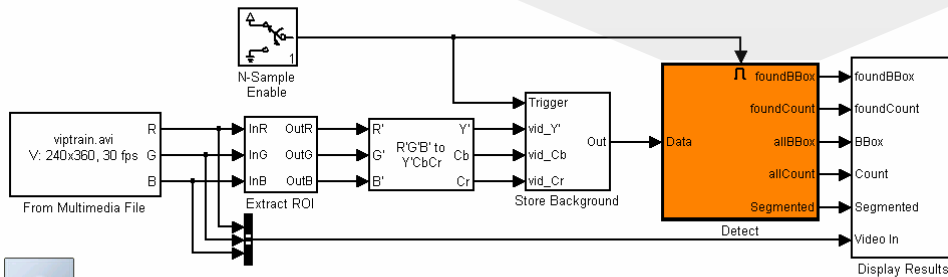
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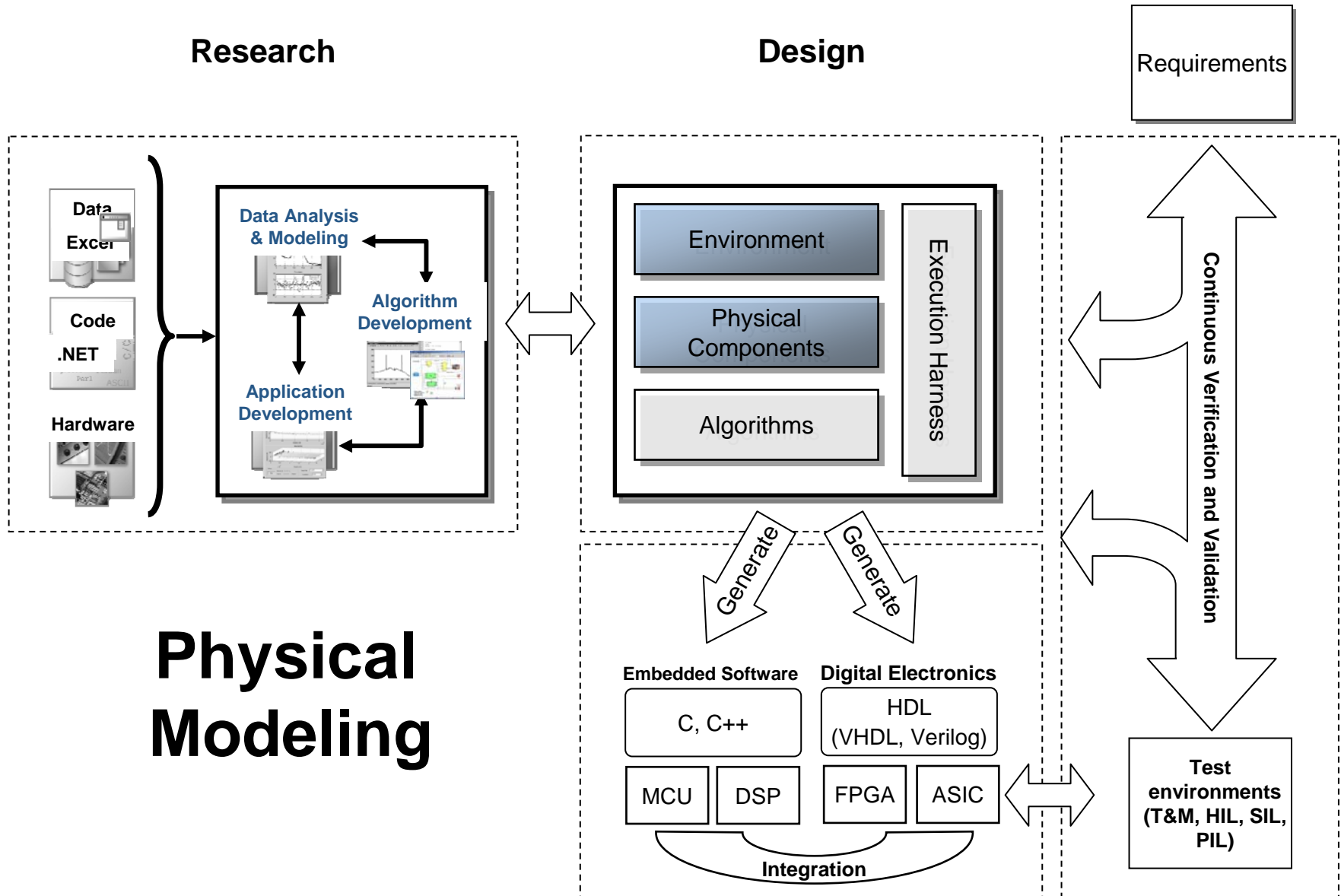
Embedded MATLAB Editor - Block: vipabandonedobj/Detect/Abandon...
File Edit Text Debug Tools Window Help
[Icons]

112 -     if track(i).hitCount >= alarmCount
113 -         OutCount = OutCount + 1;
114 -         OutBBox(:, OutCount) = track(i).bbox;
115 -     end
116 - end
117
118 - function t = empty_track
119
120 -     t.area         = int32(0);
121 -     t.centroid     = int32([0; 0]);
122 -     t.bbox         = int32([0;0;0;0]);
123 -     t.age          = int32(0);
124 -     t.hitCount     = int32(0);
125 -     t.missCount    = int32(0);
126 -     t.justHit      = false;
127 -     t.isTrackActive = false;
128
Ready                               Ln 120 Col 28 'maxNumTracks' found at 25:34
    
```

- Embedded Subset of MATLAB Language
- Floating and fixed-point
- Brings MATLAB algorithms into Simulink and Stateflow models
- C code generation with Real-Time Workshop

Abandoned Object Detection

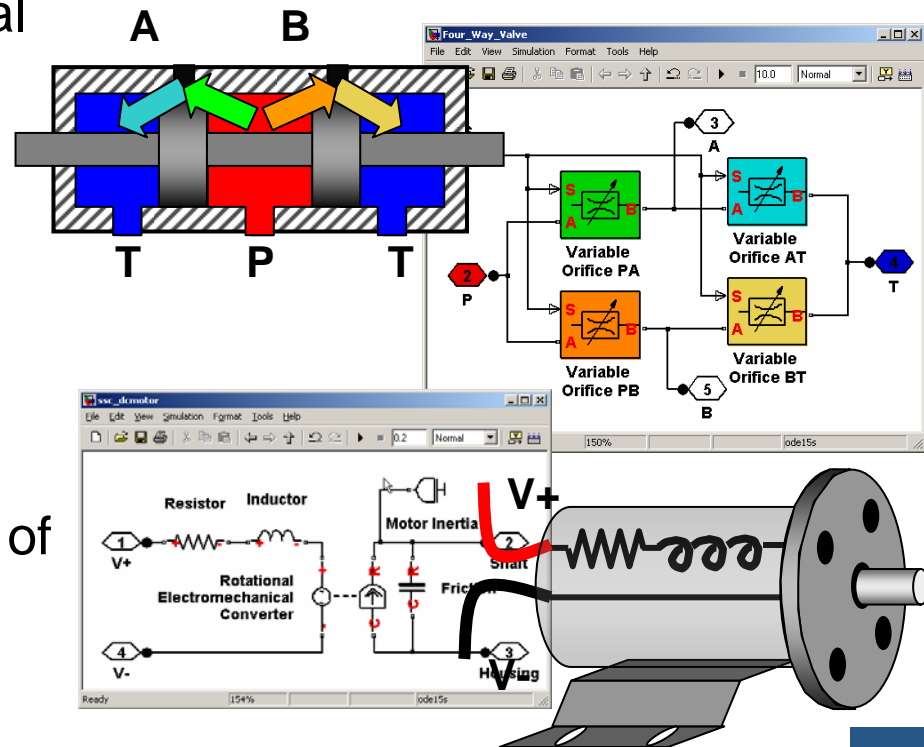
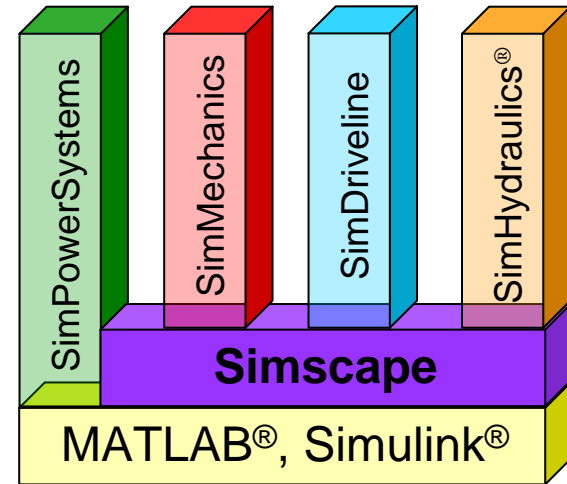




Physical Modeling

Introduction to Simscape

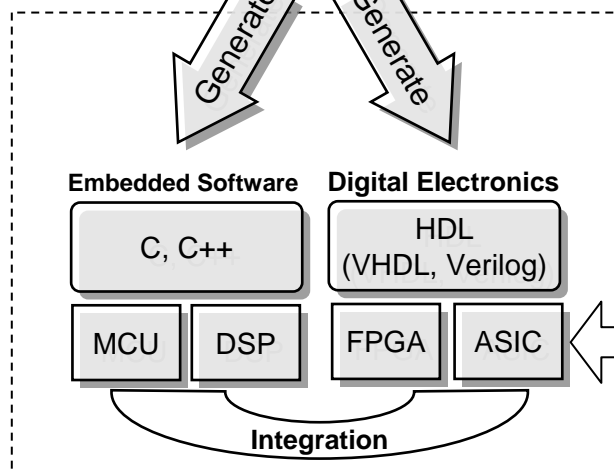
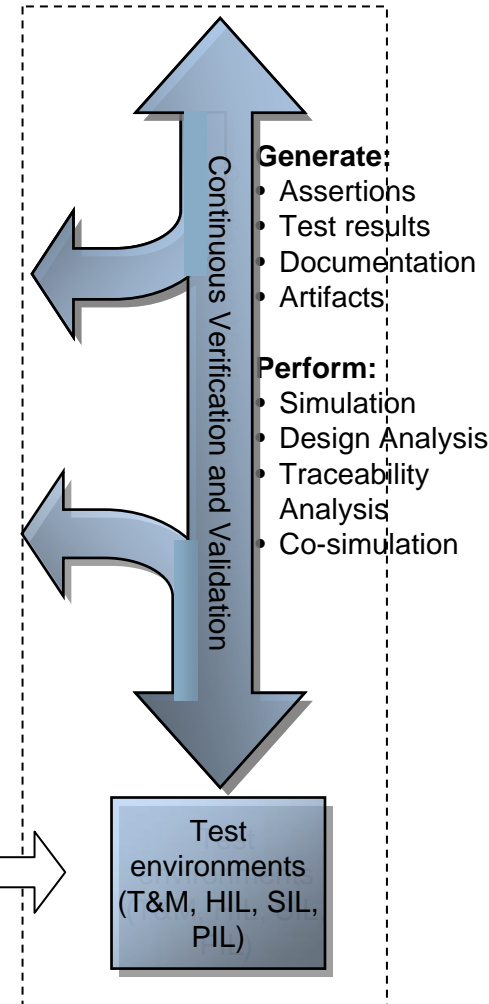
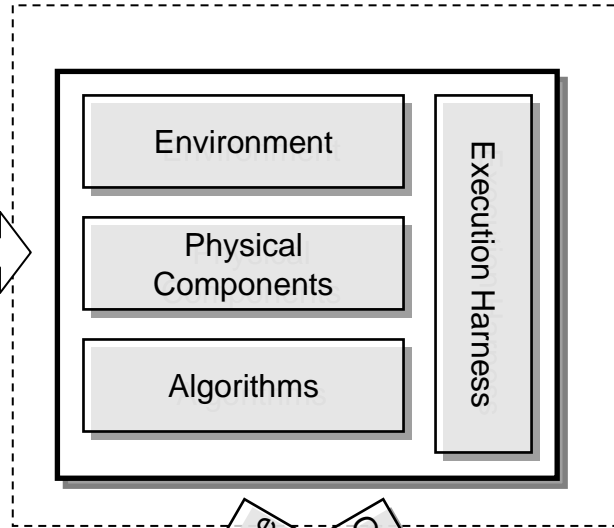
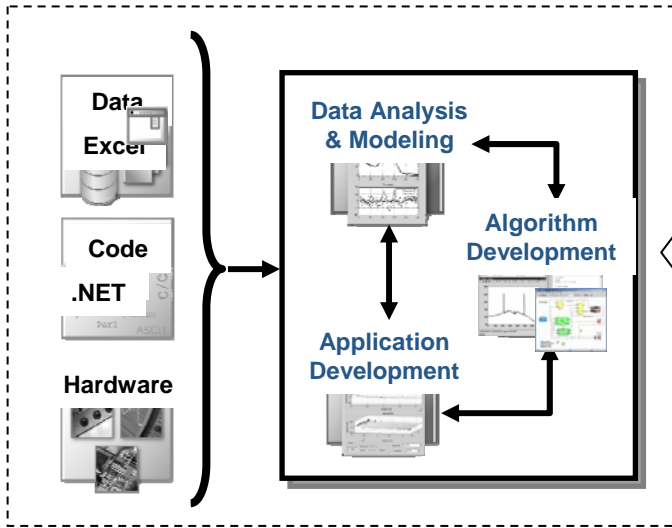
- Extension of Simulink® designed to model multidomain physical systems
- Eases process of modeling physical systems
 - Does not require deriving and programming the equations of motion for the system
- Used by system engineers and control engineers to build a model representing the physical structure of the system



Research

Design

Requirements



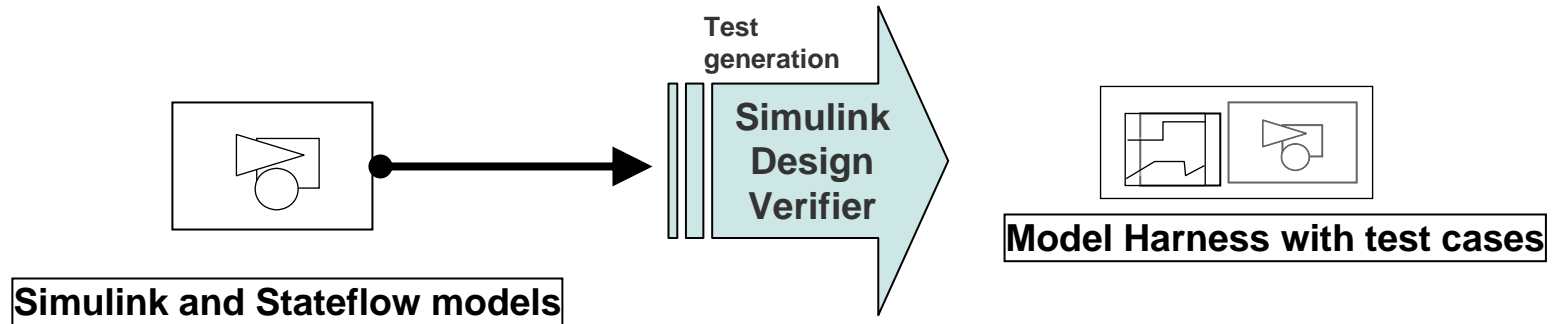
Verification & Validation

Implement

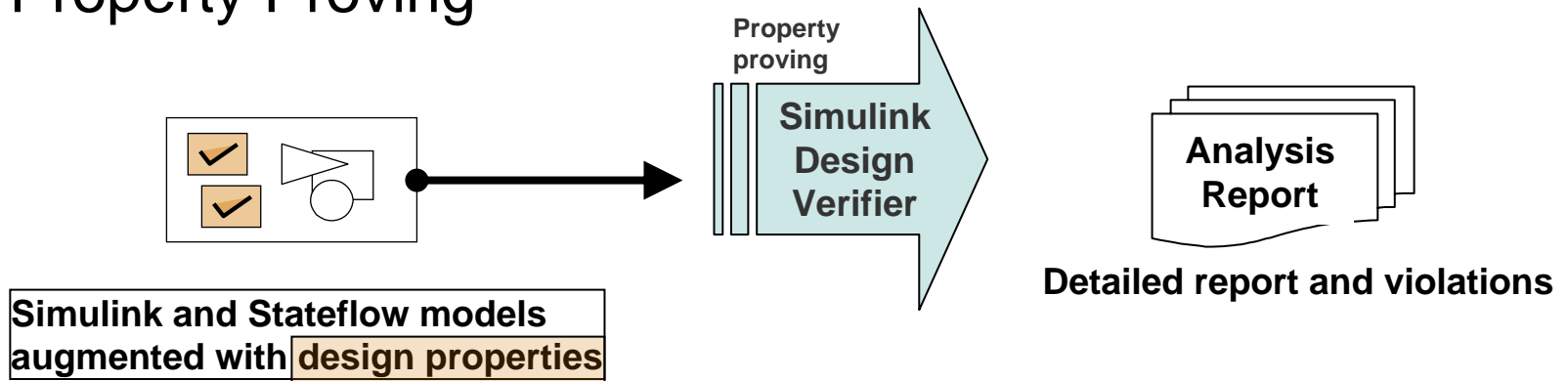
V&V

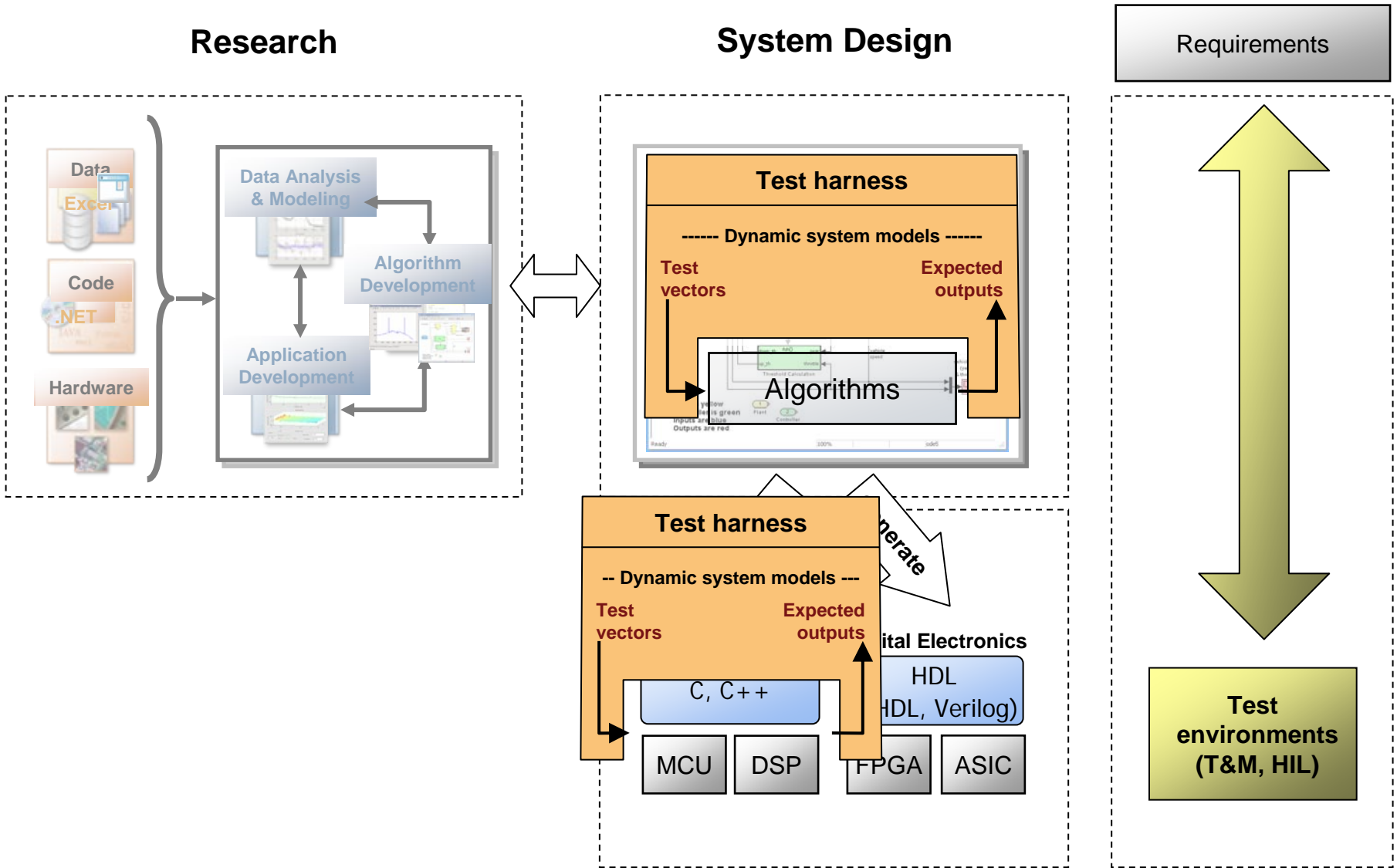
Simulink Design Verifier

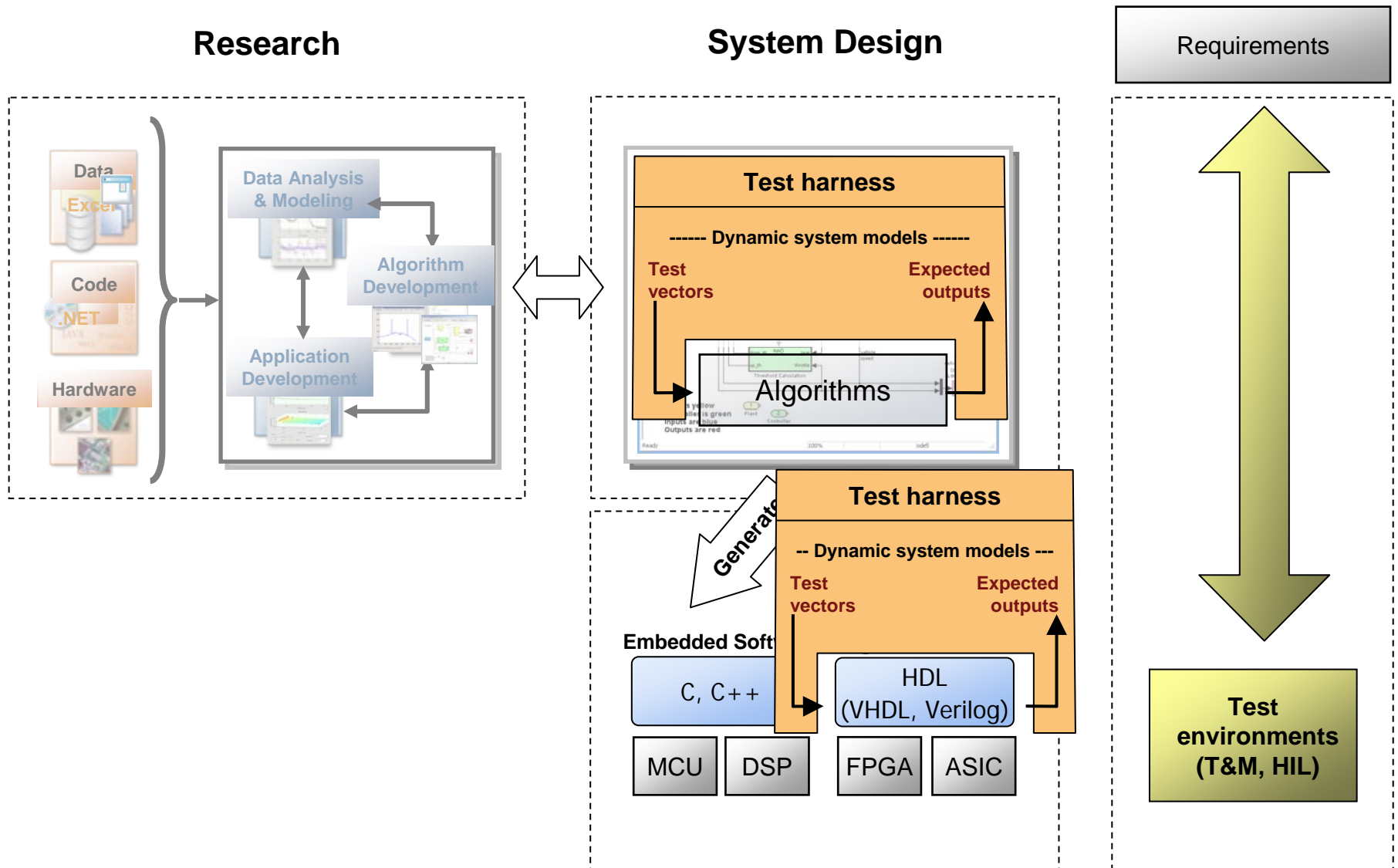
- Test Generation

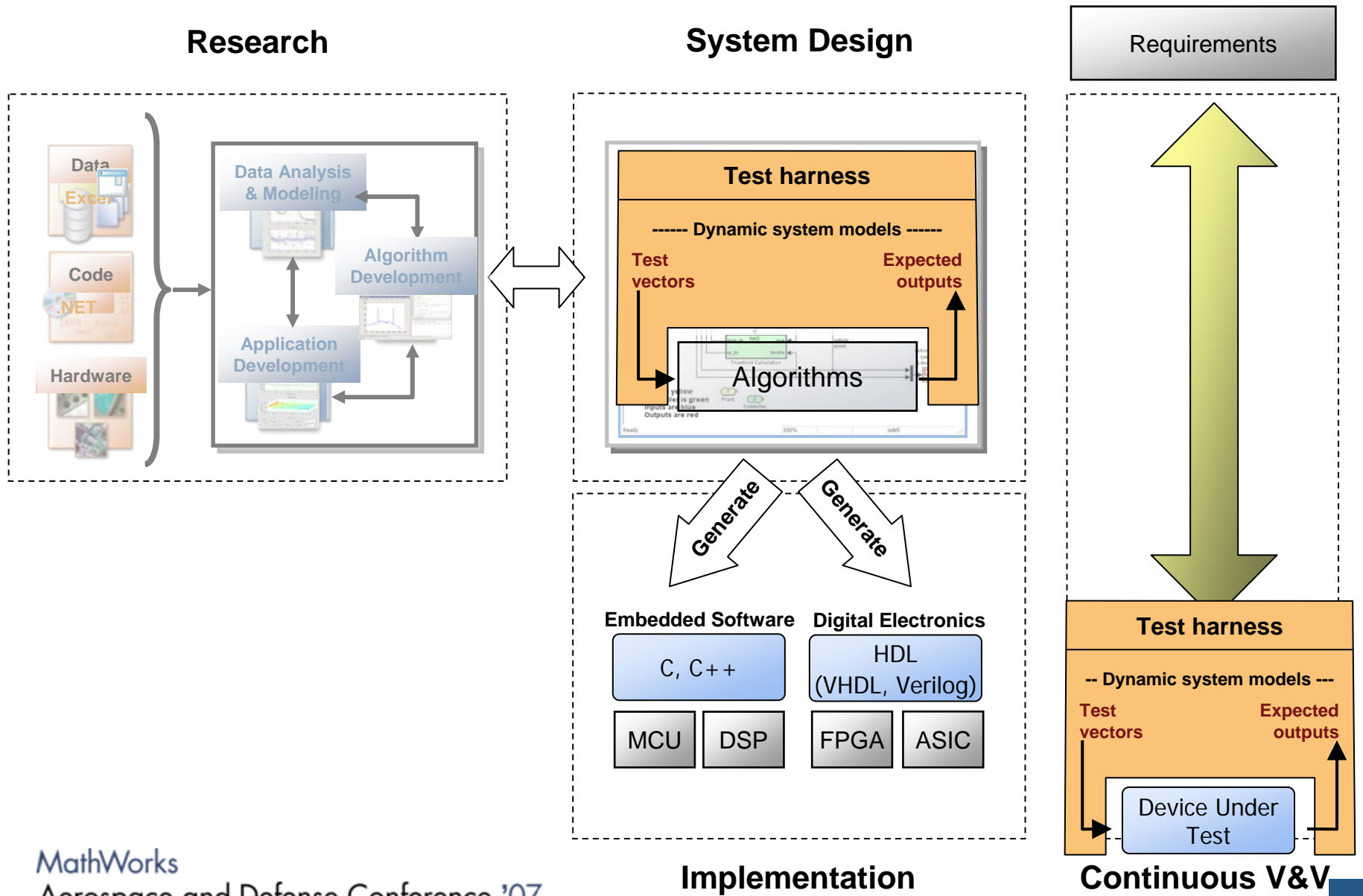


- Property Proving





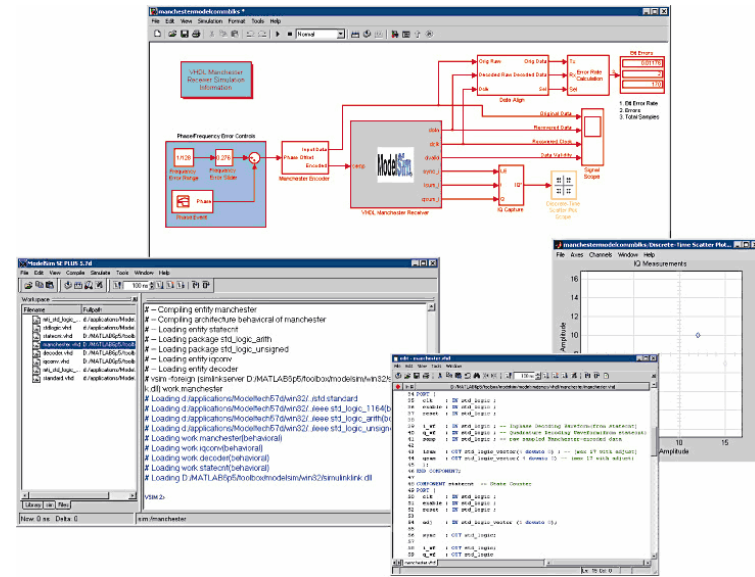




Verify Hardware and Embedded Software Implementation using Links

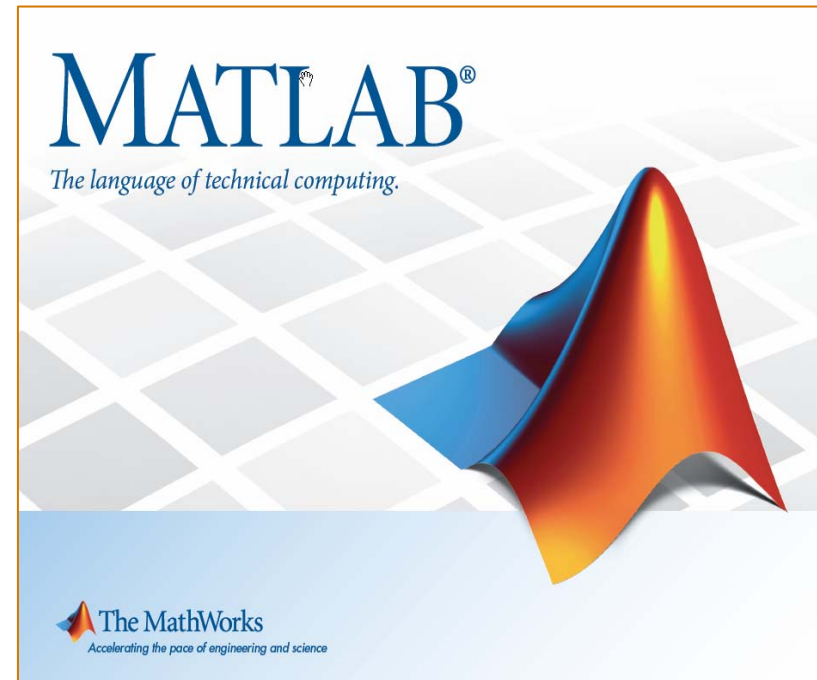
- Reuse test sequences
- Reuse model as testbench
- Cosimulate implemented component

<p>Embedded Software</p>	<ul style="list-style-type: none"> ■ TI Code Composer Studio ■ Analog Devices VisualDSP++ ■ Altium TASKING ■ xPC Target
<p>Digital Hardware</p>	<ul style="list-style-type: none"> ■ Cadence® Incisive® ■ Mentor Graphics ModelSim



Improved Product Development and Delivery Processes

- Quality focus
 - Continuous product improvement
 - Fine-tuned development processes
- Twice-yearly releases
 - 2006
 - March **R2006a**
 - September **R2006b**
 - 2007
 - March **R2007a**
- Timely delivery
 - More vehicles to address customer input
 - Predictable release schedule



How can I participate in the MATLAB and Simulink community?

Use this conference to network

- Talk to MathWorks staff (badges or blue shirts)
 - Ask about the products and their uses
 - Tell us your requirements – we're here to talk to you!
- Meet people from other organizations
 - What are they doing with MathWorks products?
- Visit the exhibit hall
 - Get a demo
 - Learn from our partners